Installation and Setting-Up Instructions Spare Parts List



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Satron Instruments Inc. P.O.Box 22, FIN-33901 Tampere, Finland Tel.int. +358 207 464 800, Telefax +358 207 464 801 www.satron.com, e-mail: info@satron.com

1 INSTALLATION

1.1 Mechanical installation

Figure 1-1

Recommended mounting position

- Calibration direction and PLUG connector's coupling direction: horizontal
- Cable entry direction: from below
- Process connection direction: horizontal
- The UP arrow on flange should point upwards



General

Flange-mounted transmitter is installed directly on the side of a tank. As a result the measurement conditions may be quite demanding. As far as possible, however, the location of the transmitter should be such that the effects of temperature variations will be as small as possible. Mechanical stresses, such as vibration, should also be avoided as far as possible.

The installation should be such that the operating temperature of the transmitter's electronics will not exceed +80°C. For example, the tank must be insulated if necessary (see Fig. 1-1). Sufficient space should be provided around the transmitter to ensure free circulation of air.

Table for Figure 1-2: Mounting accessories

- 1. Flange coupling DN80
- 2. Sealing plate DN80¹⁾
- 3. Nut

NOTE! The materials for the mountings should be chosen to withstand the ambient and process conditions.

¹⁾ The pickling of the pipework and tank should be taken into account when choosing the sealing materials. The materials should resist any absorption of the pickling material in the seal. E.g. Viton is recommended.



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Figure 1-3a Dimensional drawings (dimensions in mm)

JIS 40K-80

JIS 10K-100

JIS 40K-100

23 170

19 175

25 205





Figure 1-3b Dimensional drawings (dimensions in mm)

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SATRON VL pressure transmitter with Sandvik-Clamp:



SATRON VL pressure transmitter with flange:

The transmitter is mounted on DN80 PN40 flange coupling (counterflange) (Fig. 1-6). The connection dimensions are specified in ISO2082 and ISO2123 Standards.

Transmitters with ANSI 3" 150 lbs or 300 lbs process connection are also available.



SATRON VL pressure transmitter with Tri-Clamp :



SATRON VL pressure transmitter with M45x2 connection:



SATRON VL pressure transmitter with BA3 and BB connection:



SATRON VL pressure transmitter with SMS connection:



1.2 Electrical connections

Supply voltage and load of the transmitter according to the figure 1-15.

We recommend shielded twisted-pair cable as signal cable.

The signal cable should not be installed near high-voltage cables, large motors or frequency converters.

The shield of the cable is grounded at the power supply end or according to the recommendations of the manufacturer of the used control system.







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2 SETTING UP

2.1 Using the 275 user interface

Operation keys

The six operation keys are located above the alphanumeric keyboard:

The ON/OFF key (I/O) switches the user interface on and off. When you switch the user interface on, it starts looking for a HART® transmitter connected to it. If the transmitter is not found, the message "No Device Found. Press OK" will be displayed.

The ONLINE menu is displayed when the user interface finds the transmitter.

(^) This key allows you to move upwards in menus and scroll lists forwards.

(v) This key allows you to move downwards in menus and scroll lists backwards.

(<) This two-function key allows you to move the cursor to the left and to go back to a previous menu.

(>) This two-function key allows you to move the cursor to the right and to select a menu option.

(>>>) The quick-selection key will start the user interface and display the quick-selection menu. You can define the desired menu as quick-selection menu.

Function keys

With function keys F1, F2, F3 and F4 you can perform the program functions displayed above each function key. When you move in the software menus, the functions of these keys will change in accordance with the currently selected menu.



2.2 Setting up through HART® 275 user interface

After installing and connecting the transmitter, connect the user interface to the transmitter. The following menu is displayed:

- **1** Measurement
- 2 Configuration
- **3** Information
- 4 Diagnostics

To change the measuring range, unit damping time constant to output mode (linear/square-root), select Configuration.

The following menu is then displayed:

- 1 Range values
- 2 Detailed config

To change the measuring range, select Range values.

The selection displays the following menu:

| | - |
|----------|----------------------|
| 1 LRV | (lower range value) |
| 2 URV | (upper range value) |
| 3 LSL | (lower sensor limit) |
| 4 USL | (upper sensor limit) |
| 5 Min en | an (minimum sn |

- (minimum span) 5 Min span
- 6 Apply values

To change the measurement unit, damping time constant or output mode, select Detailed config from the Configuration menu.

The selection displays the following menu:

- 1 Damping
- 2 Pres. unit
- 3 Tempr. unit
- 4 Alarm current
- 5 Write protect
- 6 Lin. func
- 7 Diff El status
- 8 Burst mode 9 Burst option
- Poll addr
- Tag

User function

User funct. setup

After these activities or if the transmitter is supplied with the ready configuration you must correct a zero error of the transmitter in a final installation position.

Press Diagnostics and PV Zero calibr.

The selection displays the following menu: Give correct value for Zero pressure in ...

The current zero point will be shown in display and the final zero error correction can be done.

2.3 Using the 375 user interface



2.4 Setting up through HART® 375 user interface

After installing and connecting the transmitter, connect the user interface to the transmitter. The following menu is displayed: **Main menu**. To select the **HART Application**.

The following menu is then displayed:

- 1 Measurement
- 2 Configuration
- 3 Information
- 4 Diagnostics
- 5 Review

To change the measurement unit, damping time constant or output mod, select **Configuration**.

The following menu is then displayed:

- 1 Range values
- 2 Output
- 3 Tranfer function
- 4 General setup

To change the measurement unit, select Range values.

The following menu is then displayed:

- 1 LRV
 - 2 URV
 - 3 LSL
 - 4 USL
 - 5 Min span
 - 6 Apply values

To change the damping time constant, select **Output** from the **Configuration** menu.

The following menu is then displayed:

1 Damping

2 Alarm current

To change the output mode, select **Transfer function** from the **Configuration** menu.

The following menu is then displayed:

1 Lin. func

2 User function data

After these activities or if the transmitter is supplied with the ready configuration you must correct a zero error of the transmitter in a final installation position.

The First press **Diagnostics** and then **Sensor trim** and then **Zero trim**

The following text is then displayed : *WARN-Loop be removed from automatic control*

The final zero error correction can be done to select **ABORT** or **OK** on the display .

2.5 Setting up with SATRON pAdvisor -Software

If you want to use all the features of the VT_e Smart transmitter, we recommend the use of SATRON pAdvisor - Software and SATRON SI-Tool_eUSB-HART® modem.



Figure 2-4 VL pressure transmitter with display

1300354154





2.7 Set-up calibration, housing code T (with manual adjuster)

The transmitter is factory-calibrated, with 1 sec. electrical damping, for the range specified in the order. If range is not specified, the transmitter will be calibrated for the maximum range.

Zero and Span adjusters are at the end of the housing, under protective rubber shield. TEST jacks are also under protective rubber shield. Figure 2-5: housing T with PLUG connector

Checkout procedure

- See that the ripple on the supply voltage does not exceed 2.5 $V_{\rm pp}$ on 0-1000 Hz frequency range.

- Check the nameplate for the factory-calibrated
- range and zero suppression/elevation.
- If necessay, readjust the zero.



3 CALIBRATION

3.1 Adjustability

Maximum span is 25 times the minimum span for SATRON VL transmitter

Span adjustments is made from outside the housing, under the protective rubber shield (figure 3-1).

Zero suppression and elevation

Maximum zero suppression is 86 % of max.span, and maximum zero elevation is 100 % of max. span. Zero adjustments is made from outside the housing, under the protective rubber shield (figure 3-2).





Measuring range

The lower and upper range-values cannot differ from zero by more than the maximum span.

For example, range 4 transmitter whose measuring range is 0-4/100 kPa cannot be adjusted to measure 100...104 kPa pressure, because maximum span is 100 kPa.

3.2 Damping

If pulsation occurs in the measured pressure, it can be damped with the damping trimmer position D under the protective rubber shiled on the housing.



The transmitter is factory-calibrated with minimum electrical damping.

To increase the damping, turn the trimmer clockwise.

Adjusting the damping does not affect the transmitter's other calibration.

Damping adjustment :

- 1. Turn the selector switch from RUN to position D
- 2. Turn the regulating switch about $\pm 20^{\circ}$ so damping adjustment is activated. Turn the regulating switch to desired value of damping. 0 s on the left side, 60 s in the right side.
- 3. Turn the selector switch from position D to position RUN.

3.3 Calibration examples



First step is process value zero :

- 1. Turn the selector switch from position RUN to position PZ.
- 2. PV ZERO is done when the damping trimmer is turned once to both edges at least for 1 sec.
- 3. Turn the selector switch from position PZ to position RUN.





Measuring range: 0...300 kPa (range 5 transmitter). Span: 300 kPa

Procedure

- Apply zero pressure.
- 1. Turn the selector switch from position RUN to position Z.
- 2. Turn the regulating switch about ±20° so adjustment is activated.
- 3. Turn the regulating switch to a point where output is closest to 4 mA. (adjustment range on fine adjustment range is $\pm 0.75\%$ of span and speed of adjustment is $\pm 2.5\%$ of span / s)
- 4. Turn the selector switch from position Z to position RUN.
- Apply full-span pressure.
- 1. Turn the selector switch from position RUN to position S.
- 2. Turn the regulating switch about ±20° so adjustment is activated.
- 3. Turn the regulating switch to a point where output is closest to 20 mA. (adjustment range on fine adjustment range is $\pm 0.75\%$ of span and speed of adjustment is $\pm 2.5\%$ of span / s)
- 4. Turn the selector switch from position S to position RUN.
- Apply zero pressure.
- Repeat the adjustments to achieve the desired accuracy.

3.4 Liquid level measurement

Open tank

Liquid level measurement with pressure transmitter is based on the measurement of the liquid's static pressure. Static pressure does not depend on the shape or volume of the vessel. It can be calculated by multiplying the liquid's density by the liquid level and acceleration of gravity:

$$p = \rho h g$$

where p = static pressure

- $\rho = \text{density}$
 - h = height of liquid level
- g = acceleration of gravity

The pressure acting on the flange diaphragm is thus directly proportional to the height of the liquid level, and the transmitter can be calibrated to measure liquid level.

The lower limit of the liquid level is normally above the transmitter. This is taken into account through zero suppression.

- $h_1 =$ difference between maximum and minimum height of measured level (2.5 m)
- h_2 = level's minimum height from transmitter (1.5 m)
- ρ =density of measured liquid (950 kg/m³)
- g = acceleration of gravity (9.81 m/s²)

Span (p_1) and zero suppression (p_2) will then be as follows:

 $p_1 = h_1 \rho g = (2.5 \text{ m}) (950 \text{ kg/m}^3) (9.81 \text{ m/s}^2) = 23.3 \text{ kPa}$

 $p_2 = h_2 \rho g = (1.5 \text{ m}) (950 \text{ kg/m}^3) (9.81 \text{ m/s}^2) = 14.0 \text{ kPa}$

Measuring range = $p_2...(p_2 + p_1) = \frac{14 \text{ kPa...37.3 kPa}}{(140 \text{ mbar...373 mbar})}$



4. CONSTRUCTION AND OPERATION

Sensor Module

The piezoresistive sensor, which has a silicone oil fill, is isolated from the process with a diaphragm. Sensor pressure and temperature are measured with a 24-bit AD converter. Linearity and temperature effects are digitally corrected with an internal microprocessor connected to the sensor module.

The **sensor** converts pressure to electrical signal. The conversion is carried out through a Wheatstone bridge supplied with direct current. The elastic displacement produced in the bridge by the pressure causes bridge unbalance which is measured as a DC voltage signal.

Compensation includes temperature compensation and linearization. Each sensor is calibrated individually through a resistance network connection. The temperature information required by compensation is derived from a temperature measuring element located by the Wheatstone bridge.

Electronics Module

The electronics module converts the process pressure signal from the sensor module to 4-20 mA output signal. The conversion can be made in linear, square root or

inverted mode, or it can be done through user-selectable pressure/output point pairs (2-16 points).

Transmitters provided with own display (code \mathbf{N}) is equipped with operating keys that allow you to define the transmitter's all functions.

The active functions required for **signal shaping** are in a customized IC which is divided into two subblocks: amplifier block and standard-signal shaping block. The standard-signal shaping block also includes zero, span and damping adjustments.

The **interface stage** includes failure protections to ensure the transmitter's operation and nonfailure in possible failure conditions. This stage also includes the TEST and cable connections

5. PARTS LIST

When ordering spares, please quote this document's number BLV820AV and date 15.2.2013, the name and

order number of the required part, and the transmitter's serial number. Parts indicated with asterisk (*) as well as screws, nuts and seals (packings) are spare parts.



Figure 5-1 Parts list: VL with flange process connection and enclosure codes H and T





Figure 5-3 Parts list: VL with PMC 1" process connection and enclosure code N (display)





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| Number | Name | Order number | Number | Name | Order number |
|--------------------|---|----------------------------------|--------------------------|--|---|
| 1 2 * 3 4 | Sensing element Seal Device plug DIN43650 Cylinder-head screw M3 x 10 SFS2179 Zne | T1300207 72900114 51603021 | * 20 21 * 22 23 | Cover M Seal, Silicone rubber Back plate V Fastening screw M4 | T1300256 T1300387 T1300391 T1325347 |
| 7 | O-ring 20 x 2 ,Viton | 80012500 | 35 | Hex bolt, M10 x 40 SFS2064 m A4 | 54228140 |
| 8 | Seal GDM3-17,silicone | (80550847) 72900116 | * 36 | Mounting clamp NS70/76.1- SFS 2333 | 82220000 |
| * 9 | Wiring box GDM3009, DIN43650 | 72900111 | 37 38 | Hex nut M10 SFS 2067 A4 Seal EPDM | 56022810 T1051205 |
| 10 | Cylinder-head screw S M3 x 35 SFS2179 A4 | 51723053 | 38 38 * 39 | Seal FPM (Viton®) Seal PTFE Coupling Sandvik 53 mm | T1051204 T1051203 T547290 |
| 11 | Cylinder-head screw S M3 x 4 VSM 13302 Zne | 51613009 | * 39 * 39 40 | Coupling Sandvik 104 mm Coupling Sandvik 155 mm O-ring 18.64 x 3.53 FPM | T547291 T547292 8001186353 |
| * 13 | Protection cup, housing H, M and T Protection cup, housing N | T1300295 T1300400 | * 41 * 42 43 44 | * 41 Coupling PMC1" * 42 Washer 8.4 A4 DIN125 43 Hex screw M8x12 A4 44 O-ring 34.6x2.62 FPM * 45 Coupling M45x2, adjusting O-ring 41.2x3 FPM | M1050300 50002630 54228010 80013460 M1050459 800141230 |
| * 15 * 16 17 | Mounting clamp Support plate Hex nut M8 SFS2067 A4 | T544953 T543223 56022800 | * 45 | | |
| * 18 19 | Mounting bracket S O-ring, 42x2 FPM (Viton®) | T1050009 80013800 | | | |



Satron Instruments Inc. www.satron.com P.O.Box 22, FIN-33901 Tampere, Finland Tel.int. +358 207 464 800, Telefax +358 207 464 801 CE